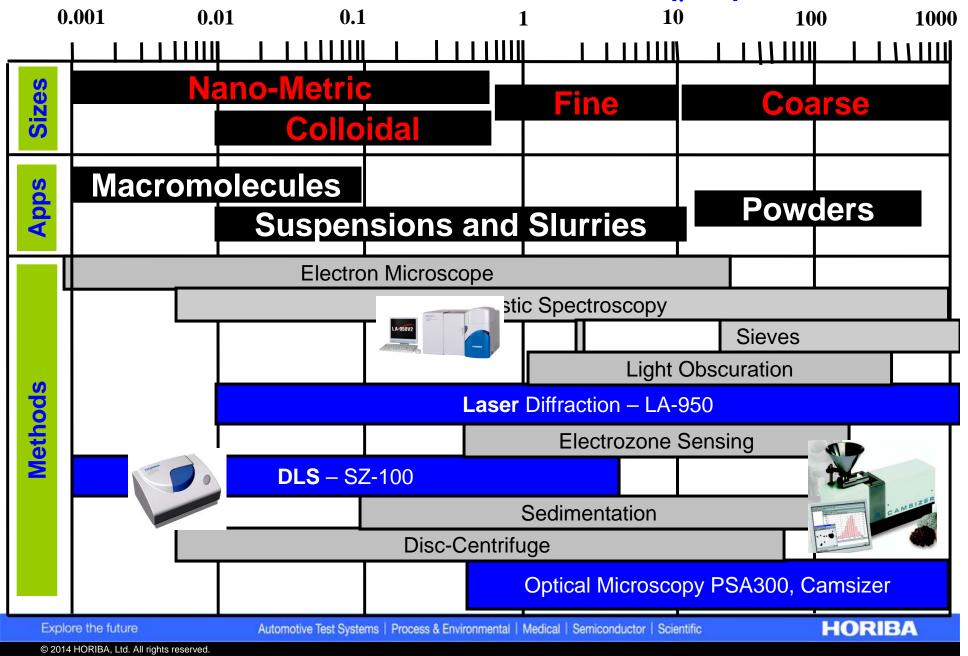


# Introduction to Image Analysis

Jeffrey Bodycomb, Ph.D.
HORIBA Scientific
www.horiba.com/us/particle

#### Size: Particle Diameter (µm)





- Replace sieves (really!)
- Verify/supplement laser diffraction results (orthogonal technique).
- Need shape information, for example due to importance of powder flow

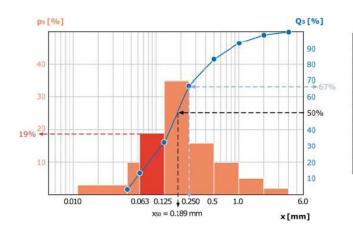


These may have the same size (cross section), but behave very differently.



#### Replace Sieves

- Tend to wear over time. It is difficult to tell when sieve results are "drifting" due to wear
- Results depend on nature of shaking and loading leading to operator to operator variations in results.
- Small number of size classes



Size class [mm]			p <sub>3</sub> [%]	Q <sub>3</sub> [%]
	<	0.045	3.0	3.0
0.045	5	0.063	10.0	13.0
0.063	-	0.125	19.0	32.0
0.125	2	0.250	35.0	67.0
0.250	2	0.500	16.0	83.0
0.500	<u> </u>	1.000	10.0	93.0
1.000	-	2.000	5.0	98.0
2.000	-	4.000	2.0	100.0
> 4.000			0.0	100.0

 $x_{50} = 0.189 \text{ mm}$ 

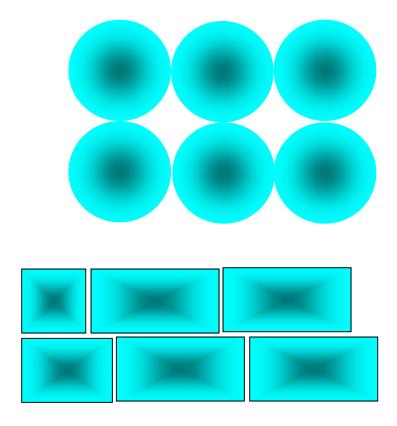




More information available through www.retsch.com



Need shape information for evaluating packing and flow.



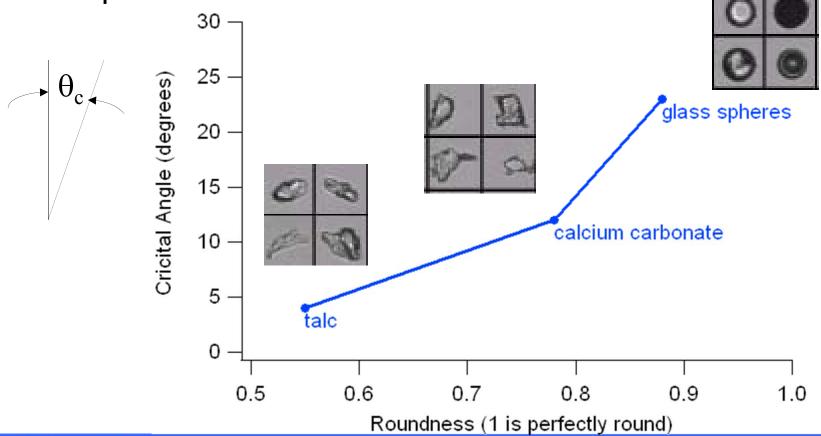
## Effect of Shape on Flow



Yes, I assumed density doesn't matter.

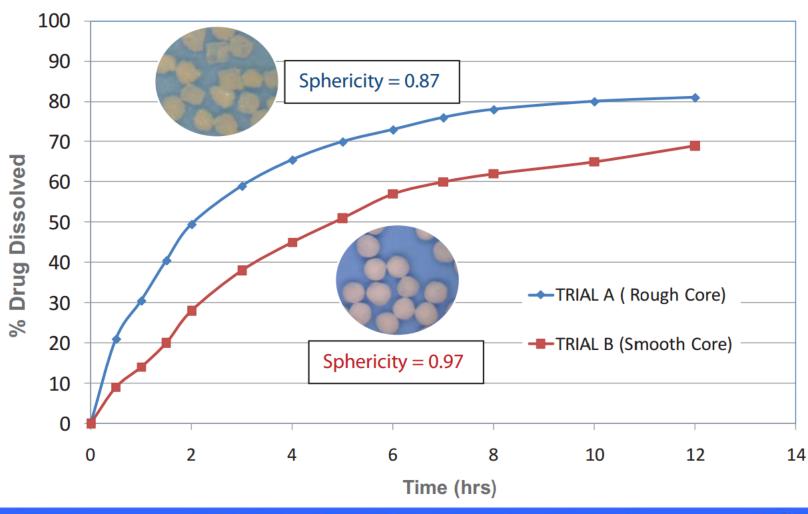
Roundness is a measure based on particle

perimeter.



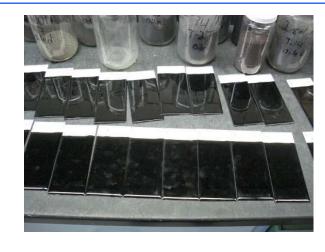


#### Shape affects drug release profile





Shape is important for roofing granules that block sunlight from reaching next layer.







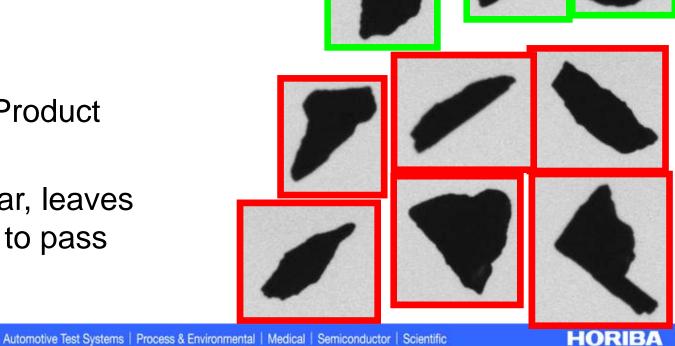


**Good Product** 

Compact particles that fully block UV

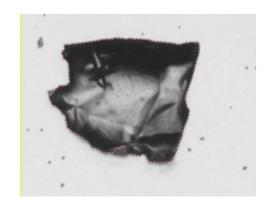
**BAD Product** 

Flaky, angular, leaves gaps for UV to pass



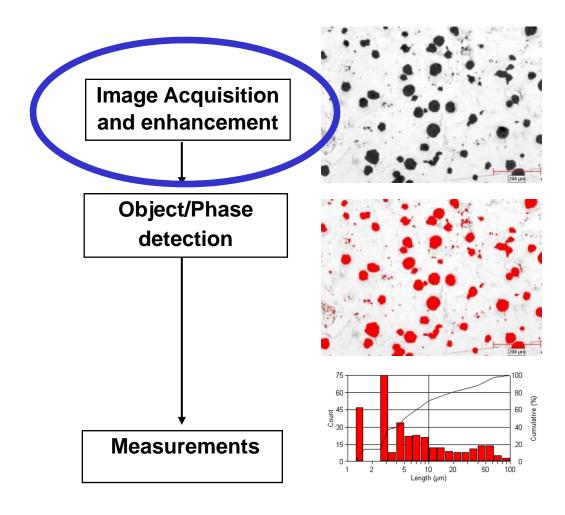


- Pictures: contaminants, identification, degree of agglomeration
- Screen excipients, full morphology
- Root cause of error (tablet batches), combined w/other techniques
- Replace manual microscopy



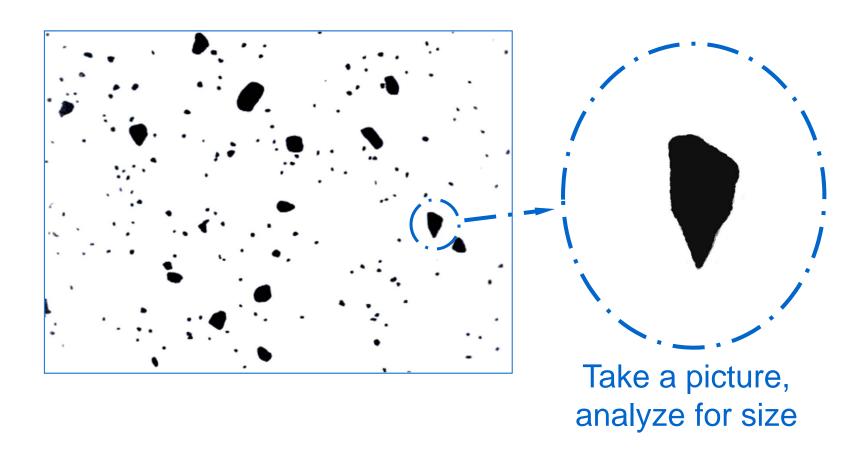
## Major Steps in Image Analysis





## Image Analysis

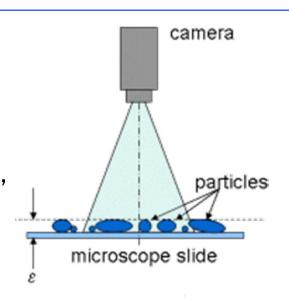




## Static Image Analysis



- Particles are dispersed (isolated)on a surface
- Picture are taken from stationary particles
- Camera or surface with particles is shifted, multiple images are taken from different positions, images are processed and evaluated
- High resolution images is possible
- Number of images/particles is limited (because of time limitations)
- Preferred orientation of the particles on the surface (largest 2D)



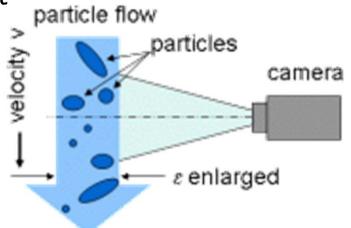


**HORIBA PSA300** 

### Dynamic Image Analysis



- Particles flow through the measurement volume of the instrument and the field of view of the camera
- Particles are captured during movement, no other moving parts necessary
- Capturing of many particle images in a short time interval
- Limitations because of image rate of the camera(s)
- Image quality is (a bit) worse
- Particles are projected in random orientation (3D)





**CAMSIZER** 

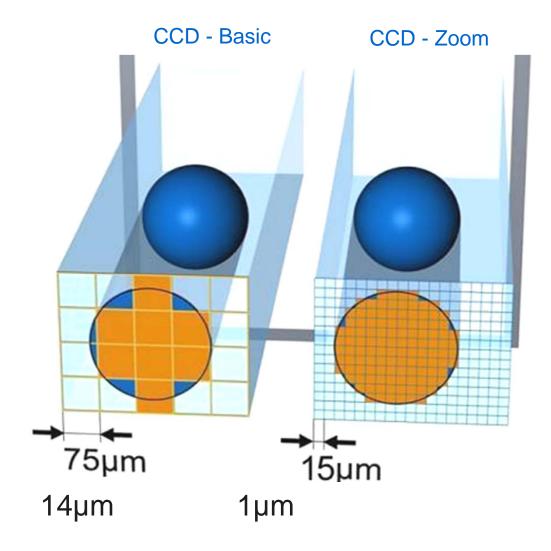
#### Resolution



Detection of particles

One pixel is element of a projection when at least half of the pixel is covered.

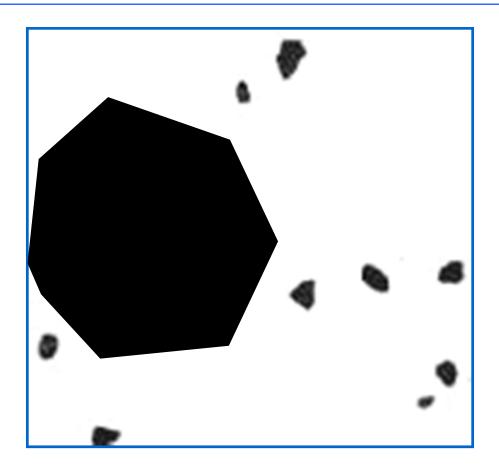
CAMSIZER
CAMSIZER XT



#### Maximum size



Large particles cannot been measured properly even they fit in the frame.



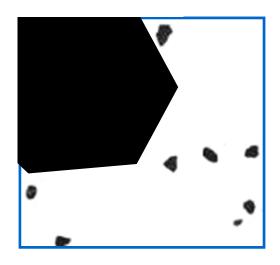
#### Maximum size

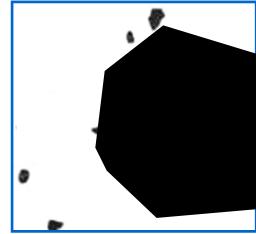


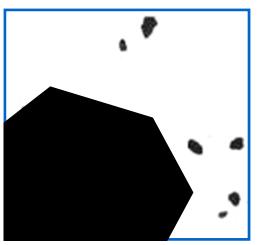
The probability of large particles touching the edge of the frame is higher than for smaller particles.

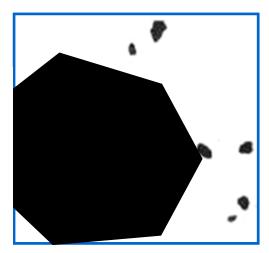
=> Large particles cannot been measured sufficiently

Upper limit of measurement range



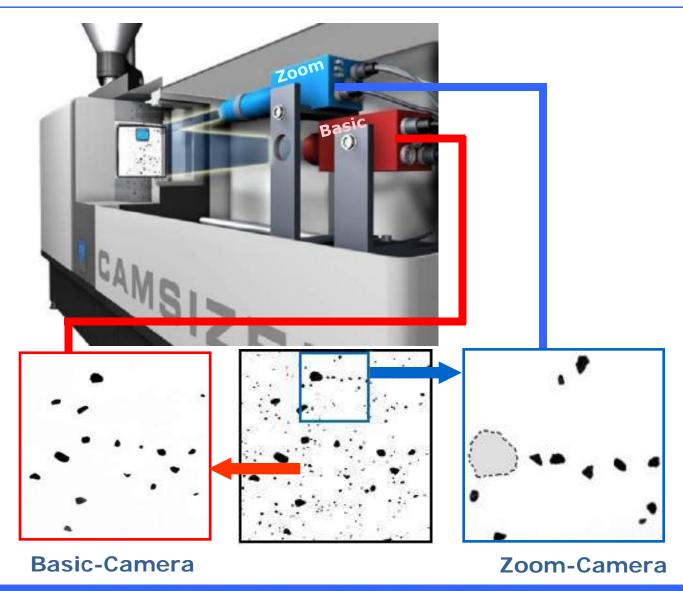






## Two-Camera-System





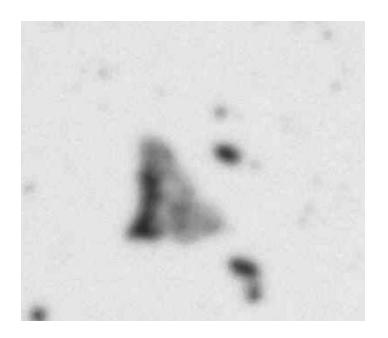
## Acquiring Images



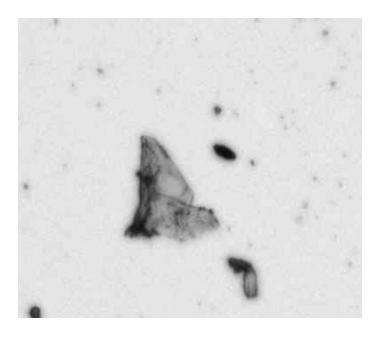
We want a good microscope and nice sharp images.

Pay attention to lighting and focus.

No

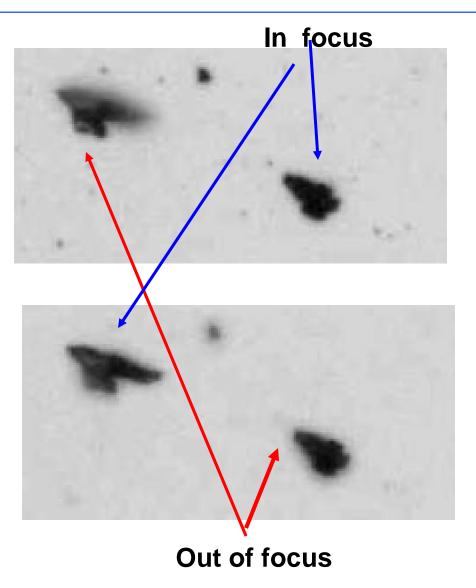


Yes



## Multilayer Grab for Sharpness







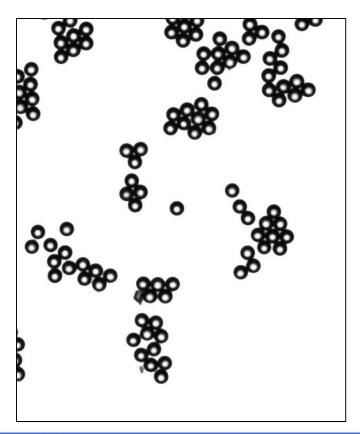
Stack images for sharper final image

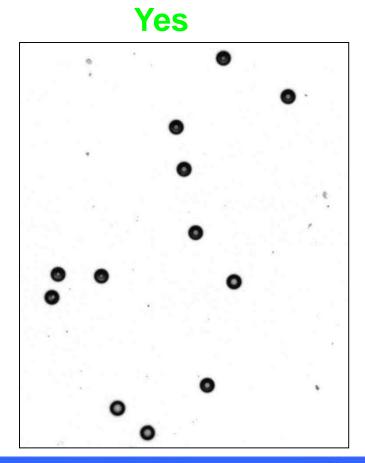
## Dispersing a Sample



Want to spread particles out so that they don't touch.

No





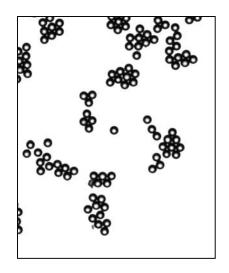
#### Control feed rate.



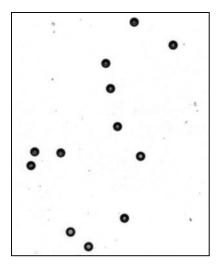
Want to spread particles out so that they don't touch.

Use % of field of view that is covered in order to control feed rate. Try 1% at first.

#### **Feeding Too fast**

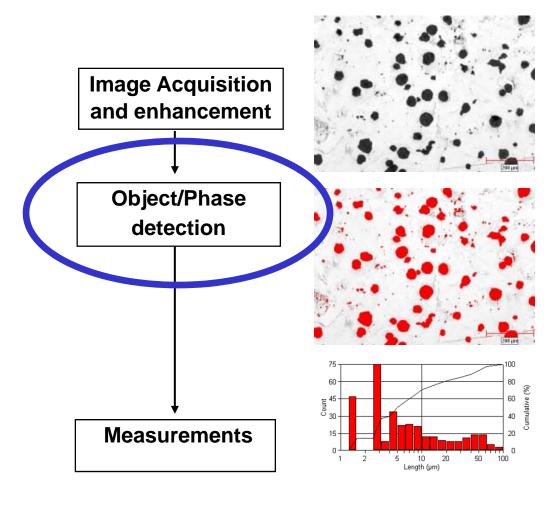


#### Good



## Major Steps in Image Analysis

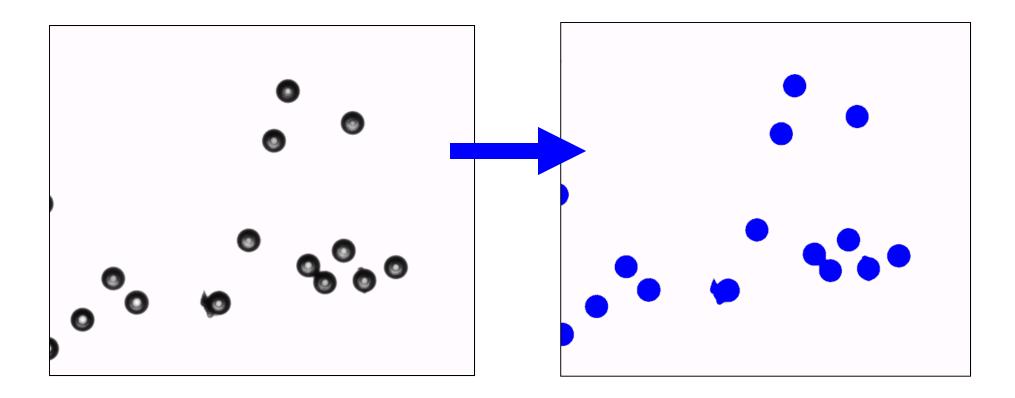




#### **Image Binarization**

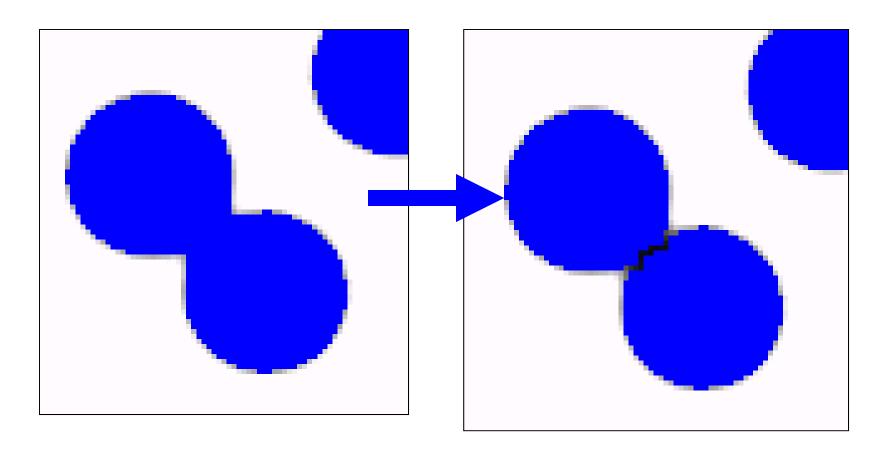


Turn into binary image (i.e., decide what is a particle and what isn't).



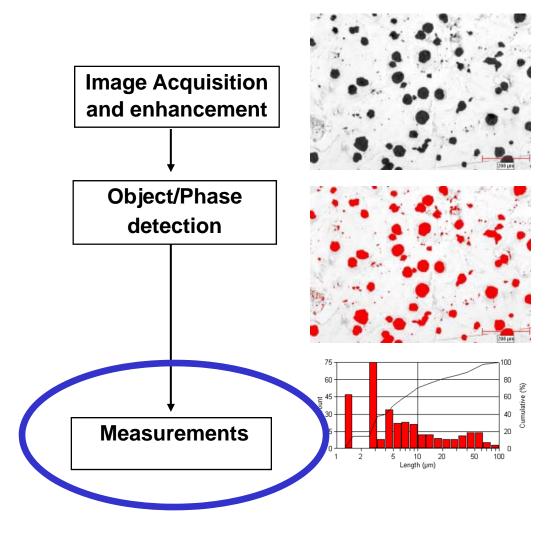
## Separation





## Major Steps in Image Analysis

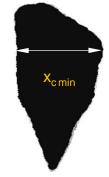




### Many Size Measures

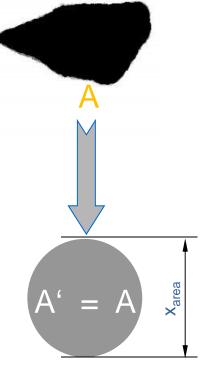




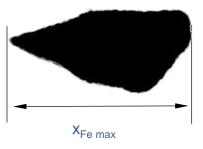


Width is best suited for comparison with sieves!





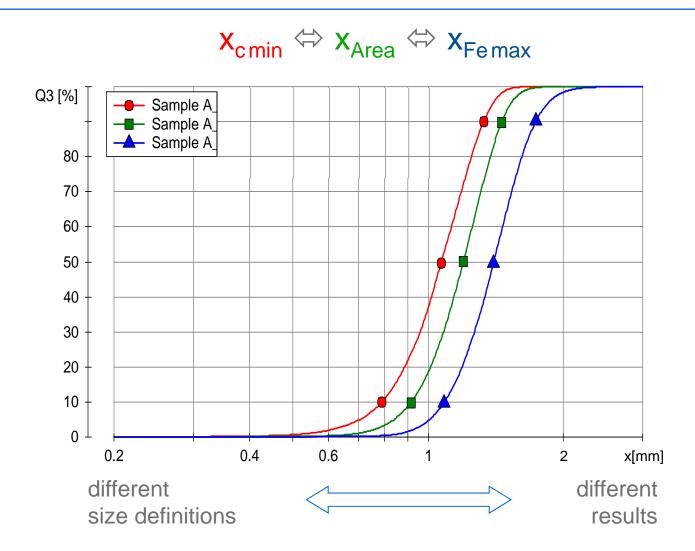
X<sub>Femax</sub>
"length"



Shape parameters can be calculated!

## Comparison of Size Definitions

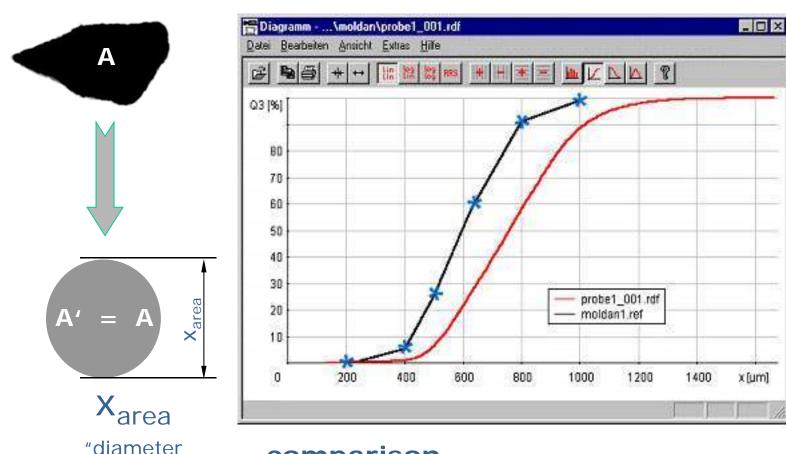




#### Digital Image Processing

#### Area Measurement ⇔ Sieving





#### comparison

CAMSIZER-measurement  $x_{area}$  (red) and sieving \* (blue)

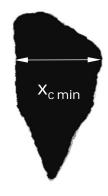
via projection surface"

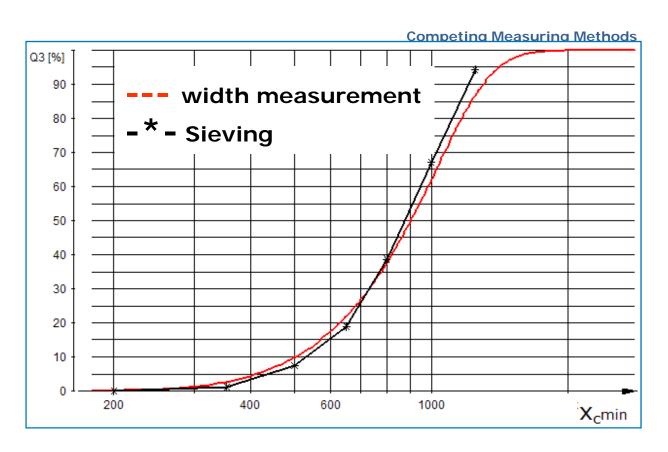
### Digital Image Processing

#### Measuring of Width ⇔ Sieving







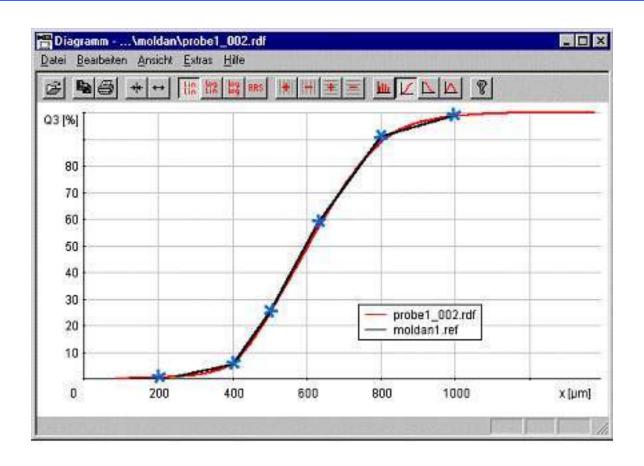


#### comparison

CAMSIZER-measurement  $x_{c min}$  (red) and sieving \* (black)

#### Fitting of CAMSIZER results to Sieving





#### fitted result

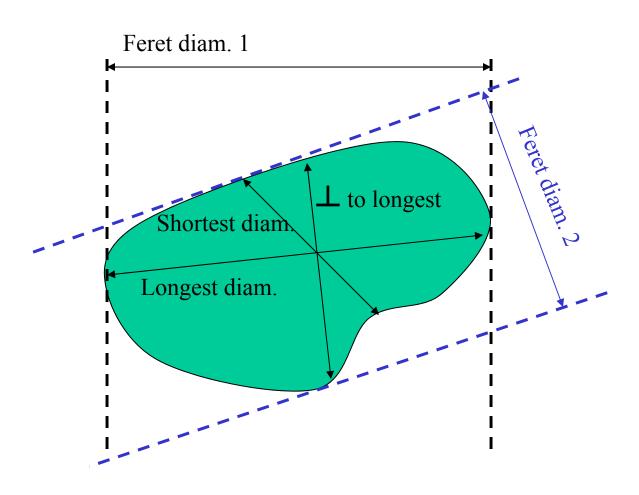
CAMSIZER-measurement x<sub>area</sub> (red) to sieving \* (blue)

## Shape: Aspect Ratio



#### Aspect ratio

- = <u>shortest diam</u> longest diam
- =<u>⊥</u> to longest diam longest diam
- = <u>shortest Feret diam</u> longest Feret diam
- = three different numbers!



## More Shape Descriptors



#### **Roundness**

A shape measure that quantifies the "roundness" of an object's edges:

$$\frac{4 \times \text{Area}}{(\pi \times \text{L} \times \text{L})}$$

#### Roughness

A shape measure that quantifies the jaggedness of an object's edges:

Convex perimeter
Perimeter

#### **Aspect Ratio**

Ratio of length over width.

$$\frac{\text{Length of longest feret}}{\text{Length of shortest feret}} = \frac{\text{Length}}{\text{Width}}$$

#### **Compactness**

Ratio of area over convex perimeter:

$$\frac{4\pi\,\mathrm{A}}{\mathrm{Convex\,perimeter}^2}$$

#### **Fractal Dimension**

Numerical characterization of irregular contours through fractal geometry.

$$P = P_{\varepsilon} \delta^{1-D}$$

D is the Fractal Dimension, d is the unit length of the scale used for the measurement and P is the perimeter of the object (1<D<2).

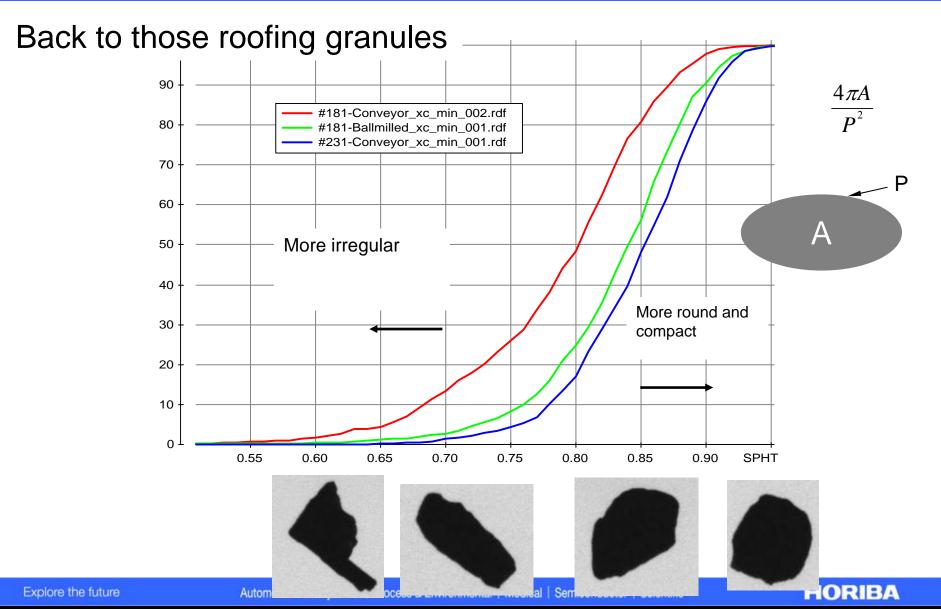
#### **Sphericity**

Estimate of the sphericity of an object:

$$\frac{4\pi A}{p^2}$$

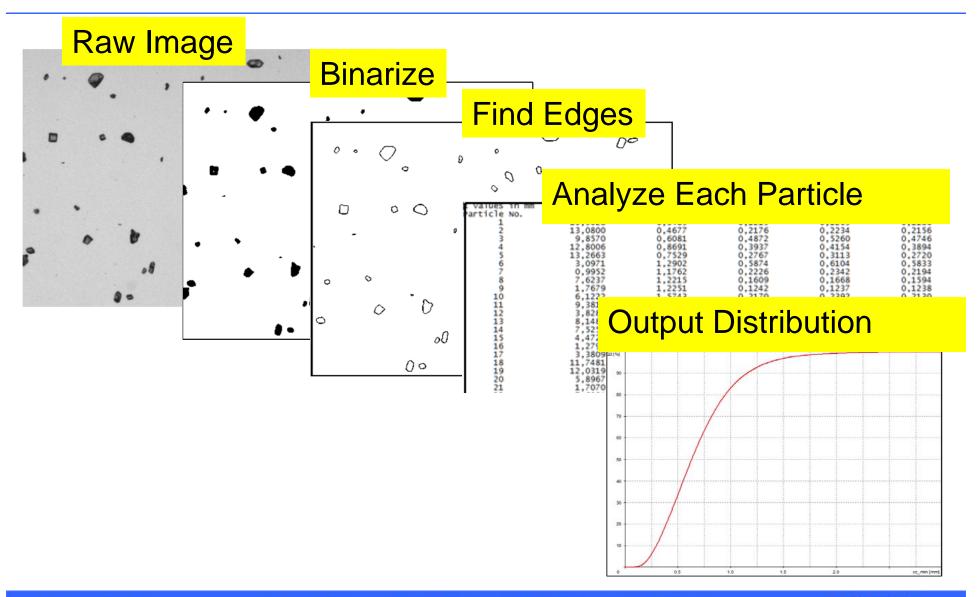
## Shape analysis





#### **Data Evaluation**



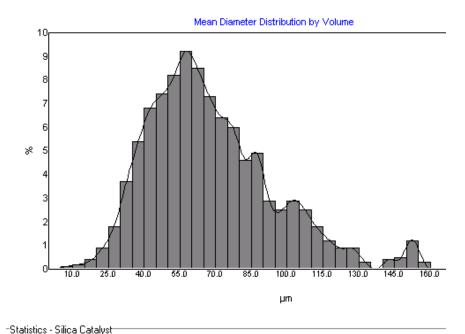


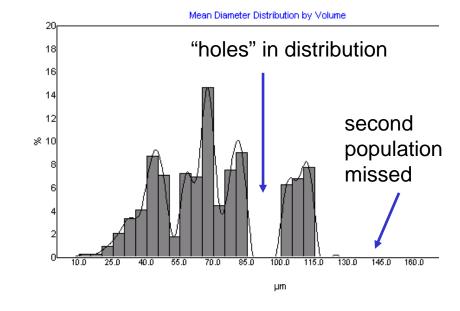
#### Effect of Number of Particles Counted HORIBA



#### 20,000 particles

#### 200 particles





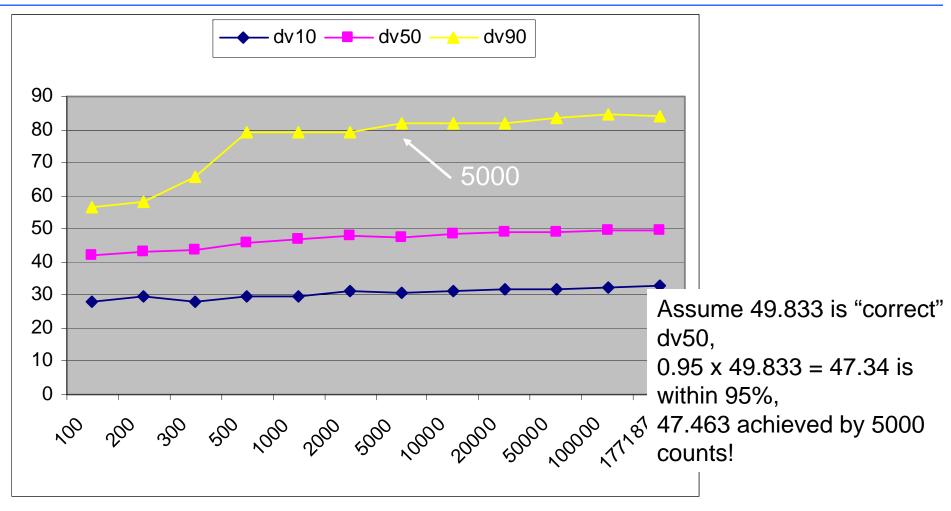
atistics - Silica Catalyst						
Mean:	27.477	D[4,3]:	68.088	Min, Ma		
STD:	22.129	D[3,2]:	57.598	Confider		
RSD:	80.539%	D[v,0.1]:	37.870	Confider		
D[n,0.1]:	4.697	D[v,0.5]:	63.467	Optics:		
Median:	23.824	D[v,0.9]:	104.351	Scanne		
D[n,0.9]:	57.814					

-Statistics - Silica C	atalyst 200			
Mean:	31.805	D[4,3]:	69.060	Min, M
STD:	21.927	D[3,2]:	58.947	Confid
RSD:	68.942%	D[v,0.1]:	39.418	Confid
D[n,0.1]:	7.021	D[v,0.5]:	68.941	Optics
Median:	29.488	D[v,0.9]:	105.901	Scann
D[n,0.9]:	63.734			

But d10, d50 &d90 may appear similar

#### More particles for more accuracy.

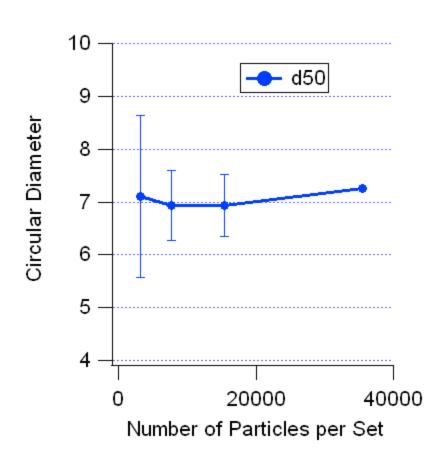




Use this to control precision of your data (and not spend extra time on precision you don't need.

### Divide Large Data Set into Smaller Sets





- Error bars are one standard deviation from repeated measurements of the same number of particles from different parts of the sample.
- The error bars get smaller as you evaluate more particles.

### **<USP> 776: Standard Deviation**



$$\sqrt{s^2 \left(\frac{n}{\chi_a^2}\right)} < \sigma < \sqrt{s^2 \left(\frac{n}{\chi_b^2}\right)}$$

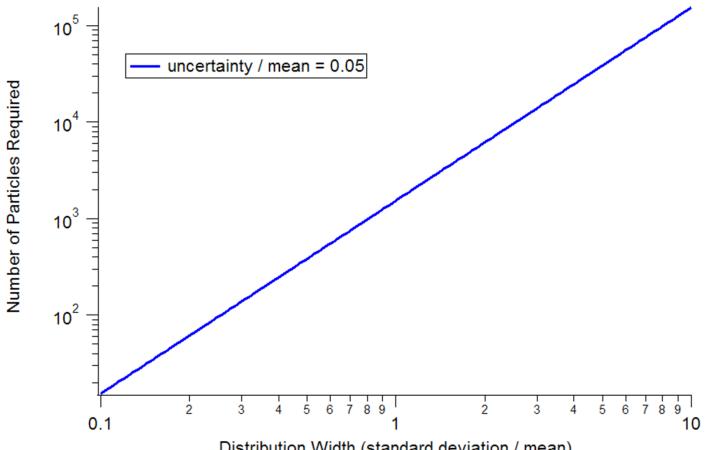
χ=Moment of chi squared distribution (see a statistics book) s=estimated standard deviation of distribution (width) n=number of particles measured

These limits are asymmetric around the standard deviation.

Implies <u>normal</u> particle size distribution, greater than 30 particles, and known standard deviation.

## **How Many Particles?**





Distribution Width (standard deviation / mean)

Some materials have a distribution such that SD/Mean ~ 1.

To obtain reliable mean values, measure ~1500 particles.

To obtain more details about the distribution, (10x?) more particles need to be measured.

## Accuracy



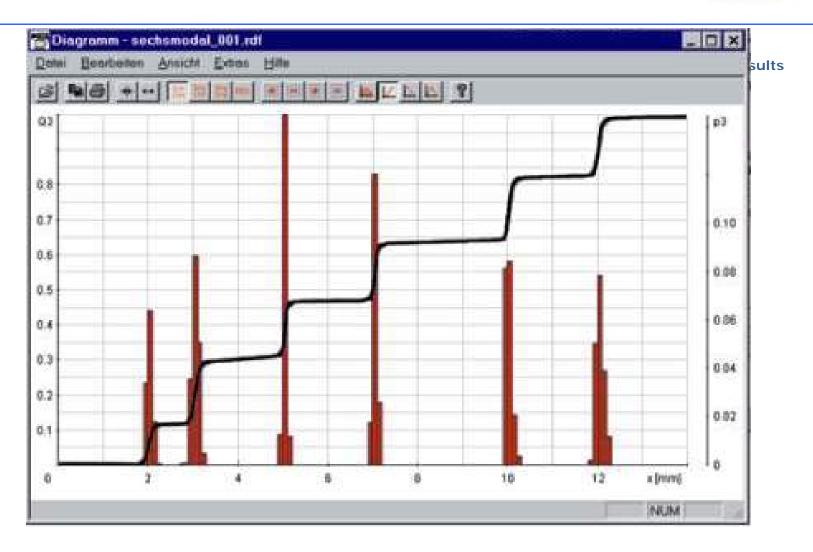
■ Is that the "real size"?

- Image analysis uses actual pictures to extract size.
- Calibration with a reticle.



#### Resolution





mixture of six sizes of grinding balls

Explore the future

## Why dynamic image analysis



- Robust measurement....the interaction between the instrument and the particle is optical, so there is no wear and change in calibration.
- High resolution size distribution results
- Fast

Also, these are all reasons to use Dynamic Image Analysis instead of sieves.

#### The HORIBA PSA300



- Turnkey System
  - More time getting results and less time engineering
- Automated
  - Faster
  - Less operator labor
  - Less operator bias
- Powerful Software Features
  - Image Enhancement
  - Particle separation
- Separate Disperser Option
  - More flexible sample preparation







#### The CAMSIZER



- Measurement of very broad particle distributions
- Direct particle definition
  - by width (analogue to sieving)
  - by length
  - or projection surface
- Two camera system for more accuracy/wider range
- Easy operation
- Fail-safe, robust
- Ideal for particle shape analyses
- Measurement of density, counting of particles



## Static or Dynamic Image Analysis?



#### Dynamic

- Broad size distributions (since it is easier to obtain data from a lot of particles)
- Samples that flow easily (since they must be dropped in front of camera)
- Powders, pellets, granules

#### Static

- Samples that are more difficult to disperse (there are more methods for dispersing the samples)
- Samples that are more delicate
- Pastes, sticky particles, suspensions

#### **Conclusions**



- ■Image Analysis is good for
  - Replacing Sieves
  - Size
  - Shape
  - Supplementing other techniques
- Watch out for
  - Sample preparation
  - ■Image quality
  - Measure enough particles



# Questions?

www.horiba.com/us/particle

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